

# **Temposonics**®

Magnetostrictive Linear Position Sensors

## R-Series V RP Profinet RT & IRT

**Data Sheet** 

- Profinet with IRT (Isochronous Real Time)
- Position + velocity measurements for up to 30 magnets
- Field adjustments and diagnostics using the new TempoLink smart assistant





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## **MEASURING TECHNOLOGY**

The absolute, linear position sensors provided by MTS Sensors rely on the company's proprietary Temposonics® magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics® position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the end of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

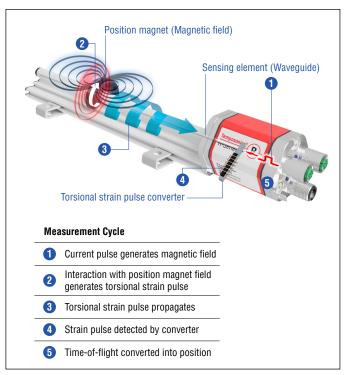


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

### R-SERIES V PROFINET RT & IRT

Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The R-Series V is the long term solution for harsh environments having high levels of shock and vibration. The sensors are available with Profinet RT (Real Time) and IRT (Isochronous Real Time). Profinet IRT offers a synchronized communication with a minimum cycle time as fast as 250  $\mu s$ . For time-critical applications R-Series V with linear extrapolation enables synchronized controller communication for any stroke length of the sensor. In addition, the sensors are available with internal linearization which offers improved linearity for overall higher accuracy of the position measurement values.

With many outstanding features the R-Series V model sensors are fit for a very broad range of applications.

## **TempoLink YOUR SMART ASSISTANT**

The TempoLink smart assistant is an accessory for the R-Series V family of sensors that supports setup and diagnostics. Depending on the sensor protocol it enables the adjustment of parameters like measurement direction, resolution and filter settings. For diagnostics and analysis of operational data the R-Series V sensors continuously track values such as total distance traveled by the position magnet, internal temperature of the sensor and the quality of the position signal. This additional information can be read out via TempoLink smart assistant even while the sensor remains operational in the application.

TempoLink smart assistant is connected to the sensor via the power connection, which now adds bidirectional communication for setup and diagnostics. The TempoLink smart assistant is operated using a graphical user-interface that will be displayed on your smartphone, tablet, laptop or PC. Just connect your Wi-Fi-enabled device to TempoLink Wi-Fi access point and go to the website URL for the user-interface.



Fig. 2: R-Series V sensor with TempoLink Smart Assistant

## **TECHNICAL DATA**

Output								
Interface	Profinet RT Profinet IRT version 2.3							
Data protocol	MTS Profile and Encoder Profile 4.1							
Data transmission rate	100 MBit/s (maximum)							
Measured value	Position, velocity / o	ption: Simultaneo	us multi-position a	nd multi-velocity m	neasurements up	to 30 magnets		
Measurement parameters								
Resolution: Position	0.5100 μm (selectable)							
Cycle time <sup>1</sup>	Stroke length         ≤ 50 mm         ≤ 715 mm         ≤ 2000 mm         ≤ 4675 mm         ≤ 6350 mm           Cycle time         250 μs         500 μs         1000 μs         2000 μs         4000 μs							
Linearity deviation <sup>2</sup>	Stroke length Linearity deviation	up to 500 mm ≤ ±50 μm	greater 500 mm < 0.01 % F.S.					
Repeatability	< ±0.001 % F.S. (min	nimum ±2.5 µm) t	ypical					
Hysteresis	$< 4 \mu m$ , typical 2 $\mu m$							
Operating conditions								
Operating temperature	-40+85 °C (-40+185 °F)							
Humidity	90 % relative humidity, no condensation							
Ingress protection	IP65 (connectors correctly fitted)							
Shock test	150 g / 11 ms, IEC standard 60068-2-27							
Vibration test	30 g / 102000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)							
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The sensor meets the requirements of the EC directives and is marked with CE							
Magnet movement velocity	Magnet slider: Max. 10 m/s; U-magnet: Any; block magnet: Any							
Design / Material		,						
Sensor electronics housing	Aluminum (painted), zinc die cast							
Sensor profile	Aluminum							
Stroke length	256350 mm (1	250 in.)						
Mechanical mounting								
Mounting position	Any							
Mounting instruction	Please consult the technical drawings on page 4 and the operation manual (document number: 551973)							
Electrical connection								
Connection type	2×M12 female connectors (5 pin), 1×M12 male connector (4 pin)							
Operating voltage	1230 VDC ±20 $\%$	(9.636 VDC) <sup>3</sup>						
Power consumption	Less than 4 W typica	ıl						
Dielectric strength	500 VDC (DC ground to machine ground)							
Polarity protection	Up to -36 VDC							
Overvoltage protection	Up to 36 VDC							



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 $<sup>\</sup>ensuremath{\text{1/}}$  Sensor with standard settings. Further information can be found in the

operating manual R-Series V Profinet (document number: 551973)

2/ With position magnet # 252 182

3/ Power supply must be able to provide current of 1 A for power up process

## **TECHNICAL DRAWING**

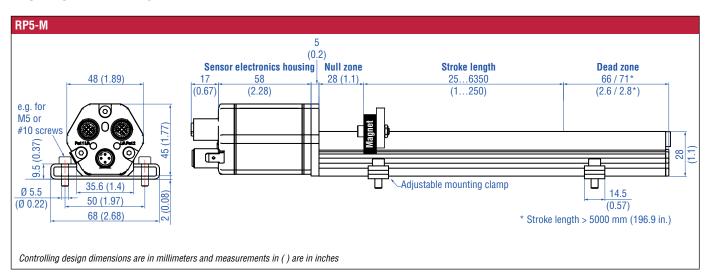


Fig. 3: Temposonics® RP5 with U-magnet

## **CONNECTOR WIRING**

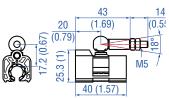
D58		
Signal		
Port 1 – M12 female connector (D-coded)	Pin	Function
	1	Tx (+)
3	2	Rx (+)
2 5 4	3	Tx (-)
	4	Rx (-)
View on sensor	5	Not connected
Port 2 – M12 female connector (D-coded)	Pin	Function
	1	Tx (+)
3	2	Rx (+)
(2) (5) (4)	3	Tx (-)
	4	Rx (-)
View on sensor	5	Not connected
Power supply		
M12 male connector (A-coded)	Pin	Function
	1	1230 VDC (±20 %)
	2	Not connected
	3	DC Ground (0 V)

Fig. 4: Connector wiring D58



## FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Guide 551444

### **Position magnets**



57 (2.24) 14 49 (1.93) 0.55 W5 W5 W5 W5 W5 W5 20 (1.69) (0.94) (0.79)

42 15.2 (1.65) (0.6) 20 (0.79)

#### Magnet slider S, joint at top Part no. 252 182

Material: GRP, magnet hard ferrite Weight: Approx. 35 g Operating temperature: -40...+75 °C (-40...+167 °F) Magnet slider V, joint at front Part no. 252184

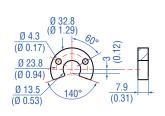
Material: GRP, magnet hard ferrite Weight: Approx. 35 g Operating temperature: -40...+75 °C (-40...+167 °F)

### Magnet slider N longer ball-joint arm Part no. 252 183

Material: GRP, magnet hard ferrite Weight: Approx. 35 g Operating temperature: -40...+75 °C (-40...+167 °F) Magnet slider G, backlash free Part no. 253 421

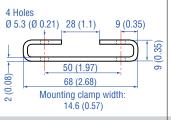
Material: GRP, magnet hard ferrite Weight: Approx. 25 g Operating temperature: -40...+75 °C (-40...+167 °F)

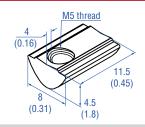
## **Position magnets**



## 

### **Mounting accessories**





### U-magnet 0D33 Part no. 251 416-2

Material: PA ferrite GF20
Weight: Approx. 11 g
Surface pressure: Max. 40 N/mm²
Fastening torque for M4 screws: 1 Nm
Operating temperature:
-40...+105 °C (-40...+221 °F)

### Block magnet L Part no. 403 448

Material: Hard ferrite Weight: Approx. 20 g Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+75 °C (-40...+167 °F)

This magnet may influence the sensor performance specifications for some applications.

### Mounting clamp Part no. 400 802

Material: Stainless steel (AISI 304)

## Part no. 401 602

Fastening torque for M5 screw: 4.5 Nm

52

(2.05)

#### Cable connectors 4

M12 D-coded male connector

Material: Zinc nickel-plated Termination: Insulation-displacement

Wire: 24 AWG - 22 AWG Operating temperature:

Fastening torque: 0.6 Nm

-25...+85 °C (-13...+185 °F)

Ingress protection: IP65 / IP67

Cable Ø: 5.5...7.2 mm (0.2...0.28 in.)

(4 pin), straight

Part no. 370 523

(correctly fitted)

# 53 (2.09)

## M12 A-coded female connector (5 pin), straight

Part no. 370 677

Material: GD-Zn. Ni Termination: Screw Contact insert: CuZn Cable Ø: 4...8 mm (0.16...0.31 in.) Wire: 1.5 mm<sup>2</sup> Operating temperature: -30...+85 °C (-22...+185 °F) Ingress protection: IP67 (correctly fitted)

Fastening torque: 0.6 Nm

# (0.24)16 (0.63)

### M12 connector end cap Part no. 370 537

Female connectors M12 should be covered by this protective cap Material: Brass nickel-plated Ingress protection: IP67 (correctly fitted) • Simple connectivity to the sensor Fastening torque: 0.39...0.49 Nm





### TempoLink smart assistant for Temposonics® R-Series V Part no. TL-1-0-EM12

- · Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic
- via 24 VDC power line
- User friendly interface for mobile devices and desktop computers
- · Rugged ABS plastic construction for the industrial environment
- See product brief "TempoLink smart assistant" (document part no.: 551976) for further information

#### **Cables**



PUR cable PVC cable Part no. 530 125 Part no. 530 108

Material: PUR jacket; green Features: Cat 5, highly flexible Cable Ø: 6.5 mm (0.26 in.) Cross section:  $2 \times 2 \times 0.35$  mm<sup>2</sup> (22/7 AWG) Operating temperature: -20...+60 °C (-4...+140 °F)

Material: PVC jacket; gray Features: Shielded, flexible Cable Ø: 4.9 mm (0.19 in.) Cross section: 3 × 0.34 mm<sup>2</sup> Operating temperature: -30...+80 °C (-22...+176 °F)



Cable with M12 D-coded male connector (4 pin), straight - M12 D-coded, male connector (4 pin), straight Part no. 530 064

Material: PUR jacket; green Features: Cat Se Cable length: 5 m (16.4 ft) Cable Ø: 6.5 mm (0.26 in.) Ingress protection: IP65, ÍP67, IP68 (correctly fitted) Operating temperature: -30...+70 °C (-22...+158 °F)



Cable with M12 D-coded male connector (4 pin), straight - RJ45 male connector, straight Part no. 530 065

Material: PUR jacket; green Features: Cat Se Cable length: 5 m (16.4 ft) Cable Ø: 6.5 mm (0.26 in.) Ingress protection M12 connector: IP67 (correctly fitted) Ingress protection RJ45 connector: IP20 (correctly fitted) Operating temperature: -30...+70 °C (-22...+158 °F)

Controlling design dimensions are in millimeters and measurements in ( ) are in inches

## **ORDER CODE**

1 2 3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
R P 5										D	5	8	1	U	4		
a	b	C			d			E	;		f		g			h	

## a | Sensor model R P 5 Profile

## Design

- G Magnet slider, backlash free (part no. 253 421)
- Block magnet L (part no. 403 448)
- U-magnet, OD33 (part no. 251 416-2)
- Magnet slider, longer ball-jointed arm (part no. 252 183)
- No position magnet
- Magnet slider, joint at top (part no. 252 182)
- Magnet slider, joint at front (part no. 252 184)

## c | Mechanical options

- **A** Standard
- Fluorelastomer seals for the electronics housing

## Stroke length

X X X X M 0025...6350 mm

Standard stroke length (mm)*	Ordering steps				
25 500 mm	25 mm				
5002500 mm	50 mm				
25005000 mm	100 mm				
50006350 mm	250 mm				
X X X X U 001.0250	.0 in.				

Standard stroke length (in.)*	Ordering steps	
1 20 in.	1 in.	
20100 in.	2 in.	
100200 in.	4 in.	
200 250 in	10 in	

## **Number of magnets**

## f | Connection type

**D 5 8** 2×M12 female connectors (5 pin), 1 × M12 male connector (4 pin)

g	System
1	Standard

h	Output	
U	4 0 1	Profinet RT & IRT with encoder profile (single position)
U	4 0 2	Profinet RT & IRT with MTS profile (single- & multi-position)
U	4 1 1	Profinet RT & IRT with encoder profile (single position) and internal linearization
U	4 1 2	Profinet RT & IRT with MTS profile (single- & multi-position) and internal linearization

### NOTICE

- For multi-position measurement the MTS profile for protocol options is required.
- · Please specify magnet numbers for your sensing application and order separately.
- The number of magnets is limited by the stroke length. The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- · Use magnets of the same type for multi-position measurement, e.g. 2 × U-magnets (part no. 251416-2).

Accessories have to be ordered

separately.

### **DELIVERY**



- Sensor
- Position magnet (not valid for RP5 with design "0")
- · 2 mounting clamps up to 1250 mm (50 in.) stroke length
- + 1 mounting clamp for each 500 mm (20 in.) additional

stroke length **X** 01...30 Position(s) (1...30 magnet(s))

<sup>\*/</sup> Non standard stroke lengths are available; must be encoded in 5 mm / 0.1 in. increments



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