Product Data



JVL ...when motors must be controlled

DC Motor Controller DMC10



DMC10 is a compact, programmable DC servo motor controller.

The DMC10 features control via either the built-in RS232 interface or an analog input (+/-10V).

In addition, the DMC10 can be controlled as a step motor system controller via a steppulse and direction input.

The DMC10 can be configured for absolute/relative positioning via 4 inputs.

DMC10 accepts a balanced or unbalanced signal from a standard 2-channel incremental encoder.

All inputs and outputs are optically isolated and overload protected.

The DMC10 has 4 generalpurpose outputs. These can be configured to provide a signal, for example, when the motor has reached a required position, or an error signal if a condition arises that prevents motor operation.

The DMC10 can be mounted in a 19" rack or on a suface

- Digital control loop
- EMC protected CE approved
- Preprogrammed speed profiles
- Can handle motors up to 1kW
- Automatic Zero-point seek
- Setup stored in EEPROM

- Following input features: Analog +/-10V
 Step-pulse and direction Digital selection of position
- RS232 Interface
- Current overload protection
- Current: 12A continuous, 25Apeak
- Short-circuit and thermal protection
- End-of-travel inputs
- Voltage overload protection
- Small physical dimensions
- Absolute/Relative positioning
- Extremely precise positioning

LD0001-05GB Date: 30-12-04

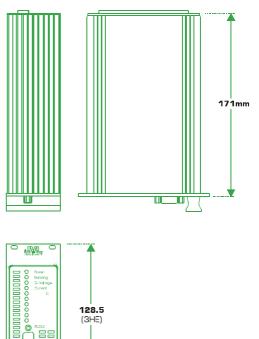


DC Motor Controller DMC10

Connector Pin Designations

(DIN 41612 Ver. B) Power Supply In 2B зА 4B 5B -4A М+ 5A DC Motor 8B 9B PDO] **Power Dump Output** 0 0 11B 12B . . 14B • • 14A — **5VO** • • " 14A — 5VO • • | 15A — EZ1 • • | 16A — EZ2 • | 17A — EA1 Reserved — 15B 16B 17B-EncoderInput **.** 18A-Balanced/Unbalanced **04** — 18B - FA2 03 — 19B — 19A — 1 -EB1 **User Outputs** 21A — ECM -ссм - CLK Step and Direction Input IN8 — 24B — 24A — DCN IN7 — 25B — 25A — DIR 24A — DCM — 26B ₩ • IN6 — 26B — — — 27A — O5V IN4 — 28B — — 28A — CO UserInputs Pulse and Direction Output OCM +/-10VInput - ACM TT2085GB

Physical Dimensions



Technical Data

Description	Min.	Max.	Units
Supply Voltage:	15	80	VDC
Continuous Motor Current:	0	12	А
Peak Motor Current:	0	25	Α
Max. Power Loss in Driver:	0	25	W
Motor Voltage:	0	85	V
Continuous "Power dump"	-	100	W
PWM Frequency:	22	23	kHz
Encoder Frequency:	0	500	kHz
Pulse Input - Frequency:	0	500	kHz
Encoder Supply (14A):	4.8	5.2	VDC
Temperature Protection:	-	75	°C
Weight:	-	720	gr.
Operating Temperature:	0	50	°C
User Inputs/Outputs:	4.5	30	VDC
Dimensions:	H = 128.5		mm
	D = 17	71	mm
	B = 50	0.1	mm

Accessories

Description Type
Interface Cable (9pin) RS232-9-1
Interface Cable (25pin) RS232-25-9
Mounting Plate for surface Base1
Connector Board for 19" rack
Programming Software MotoWare

TT2086GB



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