

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
- Standard
- Controllers Integrated
- Table/Arm /Flat Type
- Mini
- Standard
- Gripper/ Rotary Type
- Linear Servo Type
- Cleanroom Type
- Splash-Proof
- Controllers
- PMEC /AMEC
- PSEP /ASEP
- ROBO NET
- ERC2
- PCON
- ACON
- SCON
- PSEL
- ASEL
- SSEL
- XSEL
- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor

# RCP2-BA6/BA6U ROBO Cylinder Belt Type 58mm Width Pulse Motor

Top-Mounted Motor / Bottom-Mounted Motor

■ Configuration: **RCP2** —  — **I** — **42P** — **54** —  —  —  —

Series — Type — Encoder — Motor — Lead — Stroke — Compatible Controllers — Cable Length — Option

BA6 :Belt type Top-mounted motor  
 BA6U:Belt type Botom-mounted motor  
 I: Incremental \* The Simple absolute encoder models are labeled as "I".  
 42P: Pulse motor 42 □ size equivalent  
 54:54mm 500: 500mm 1000:1000mm (50mm pitch increments)  
 P1: PCON RPCON PSEL P3: PMEC PSEP  
 N : None P : 1m S : 3m M : 5m X □ : Custom Length R □ : Robot cable  
 NM : Reversed-home

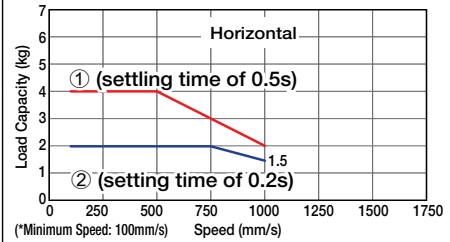
\* See page Pre-35 for explanation of each code that makes up the configuration name.



Technical References A-5

- POINT** Notes on Selection
- Operating the belt type actuator at low speeds may cause vibration and/or resonance. Therefore, please set the speed at 100mm/s or faster.
  - Since the RCP2 series use a pulse motor, the load capacity decreases at high speeds. Check in the Speed vs. Load Capacity graph to see if your desired speed and load capacity are supported.
  - The load capacity is based on operation at an acceleration of 0.5G. 0.5G is the upper limit for the acceleration.

■ Speed vs. Load Capacity  
 Due to the characteristics of the pulse motor, the RCP2 series' load capacity decreases at high speeds. In the table below, check if your desired speed and load capacity are supported.



Note:  
 Graph ① is for standard specifications, with settling time of 0.5s for calculating the positioning time.  
 Graph ② reflects some changes in the controller settings. The load capacity is lower, however the settling time is decreased to 0.2s.  
 If the load capacity is lower than graph ②, and you want to shorten the positioning time, change the controller settings. (See the manual for details.)  
 (Vertical operation is not possible.)

Actuator Specifications					
Lead and Load Capacity				Stroke and Maximum Speed	
Model	Motor Mounting Direction	Lead (mm)	Max. Load Capacity (Note 1)		Stroke (mm)
			Horizontal (kg)	Vertical (kg)	
RCP2-BA6-I-42P-54-①-②-③-④	Top	54 equivalent	~ 4	Not Allowed	500 ~ 1000 (50mm increments)
RCP2-BA6U-I-42P-54-①-②-③-④	Bottom				

Legend ① Stroke ② Compatible controller ③ Cable length ④ Options (Unit: mm/s)

① Stroke List

Stroke (mm)	Standard Price
500	-
550	-
600	-
650	-
700	-
750	-
800	-
850	-
900	-
950	-
1000	-

③ Cable List

Type	Cable Symbol	Standard Price
Standard	P (1m)	-
	S (3m)	-
	M (5m)	-
Special Lengths	X06 (6m) ~ X10 (10m)	-
	X11 (11m) ~ X15 (15m)	-
	X16 (16m) ~ X20 (20m)	-
	R01 (1m) ~ R03 (3m)	-
Robot Cable	R04 (4m) ~ R05 (5m)	-
	R06 (6m) ~ R10 (10m)	-
	R11 (11m) ~ R15 (15m)	-
	R16 (16m) ~ R20 (20m)	-

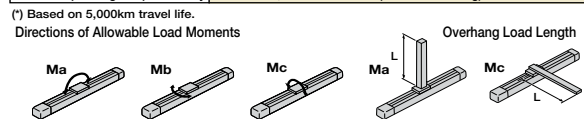
\* See page A-39 for cables for maintenance.

④ Option List

Name	Option Code	See Page	Standard Price
Reversed-home	NM	→ A-33	-

Actuator Specifications

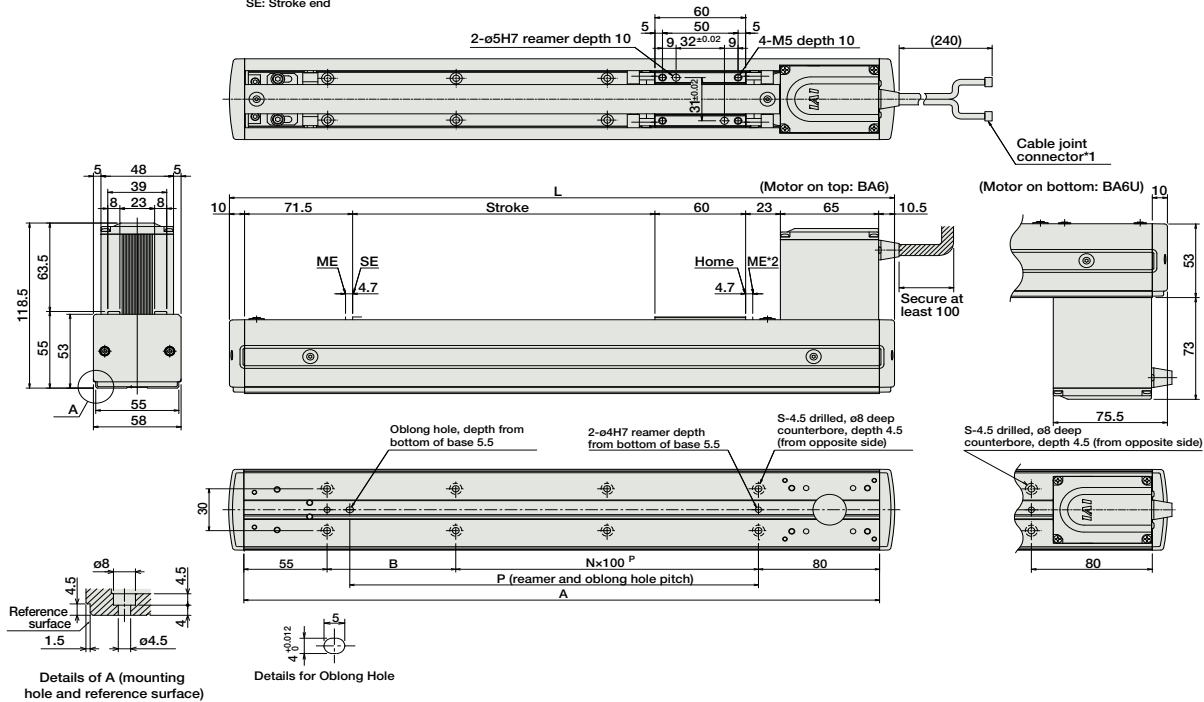
Item	Description
Drive System	Timing Belt
Positioning Repeatability	±0.1mm
Lost Motion	0.1mm or less
Allowable Dynamic Moment (*)	Ma: 8.9 N·m Mb: 12.7 N·m Mc: 18.6 N·m
Overhang Load Length	Ma direction: 150mm or less; Mb-Mc direction: 150mm or less
Ambient Operating Temp./Humidity	0~40°C, 85% RH or less (Non-condensing)



Dimensions

For Special Orders A-9

- \*1 The motor-encoder cable is connected here. See page A-39 for details on cables.
- \*2 When homing, the slider moves to the ME; therefore, please watch for any interference with the surrounding objects.  
ME: Mechanical end  
SE: Stroke end



■ Dimensions/Weight by Stroke

Stroke	500	550	600	650	700	750	800	850	900	950	1000
L	740	790	840	890	940	990	1040	1090	1140	1190	1240
A	720	770	820	870	920	970	1020	1070	1120	1170	1220
B	85	35	85	35	85	35	85	35	85	35	85
N	5	6	6	7	7	8	8	9	9	10	10
P	570	620	670	720	770	820	870	920	970	1020	1070
S	14	16	16	18	18	20	20	22	22	24	24
Weight (kg)	2.8	2.9	3.0	3.2	3.3	3.4	3.5	3.7	3.8	3.9	4.1

② Compatible Controllers

The RCP2 series actuators can operate with the controllers below. Select the controller according to your usage.

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page
Solenoid Valve Type		PMEC-C-42PI-NP-2-①	Easy-to-use controller, even for beginners	3 points	AC100V AC200V	See P481	-	→ P477
		PSEP-C-42PI-NP-2-0	Operable with same signal as solenoid valve. Supports both single and double solenoid types. No homing necessary with simple absolute type.					→ P487
Splash-Proof Solenoid Valve Type		PSEP-CW-42PI-NP-2-0						
Positioner Type		PCON-C-42PI-NP-2-0	Positioning is possible for up to 512 points	512 points	DC24V	2A max.	-	→ P625
Safety-Compliant Positioner Type		PCON-CG-42PI-NP-2-0						
Pulse Train Input Type (Differential Line Driver)		PCON-PL-42PI-NP-2-0	Pulse train input type with differential line driver support	(-)				
Pulse Train Input Type (Open Collector)		PCON-PO-42PI-NP-2-0	Pulse train input type with open collector support					
Serial Communication Type		PCON-SE-42PI-N-0-0	Dedicated to serial communication	64 points				
Field Network Type		RPCON-42P	Dedicated to field network	768 points				→ P503
Program Control Type		PSEL-C-1-42PI-NP-2-0	Programmed operation is possible Can operate up to 2 axes	1500 points				→ P557

\* This is for the single-axis PSEL.  
\* ① is a placeholder for the power supply voltage (1: 100V / 2: 100~240V).