

RCA-RGS4D

ROBO Cylinder Rod Type with Single Guide ø37mm Diameter 24V Servo Motor Built-In Model

■ Configuration: **RCA** — **RGS4D** — — — — — — — — —

Series — Type — Encoder — Motor — Lead — Stroke — Compatible Controllers — Cable Length — Option

I : Incremental
A : Absolute

20 : 20W Servo Motor
30 : 30W Servo Motor

12 : 12mm
6 : 6mm
3 : 3mm

50 : 50mm
300 : 300mm (50mm pitch increments)

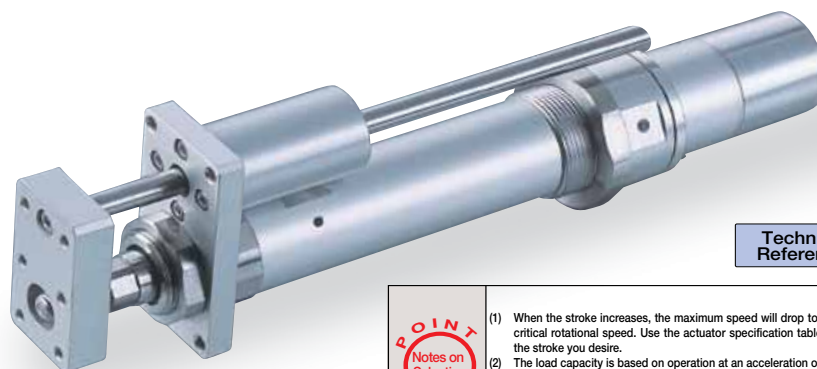
A1 : ACON
RACON
ASEL
A3 : AMEC
ASEP

N : None
P : 1m
S : 3m
M : 5m
X : Custom
R : Robot cable

See Options below

* See page Pre-35 for an explanation of the naming convention.

* The absolute models are only compatible with ASEL. Simple absolute encoders are considered incremental.



Power-saving

Technical References P. A-5



- (1) When the stroke increases, the maximum speed will drop to prevent the ball screw from reaching the critical rotational speed. Use the actuator specification table below to check the maximum speed at the stroke you desire.
- (2) The load capacity is based on operation at an acceleration of 0.3G (0.2G for the 3mm-lead model). This is the upper limit of the acceleration.
- (3) The values for the horizontal load capacity reflect the use of an external guide. See the technical resources (page A-81) for the allowable weight using the supplied guide alone.

Actuator Specifications

Lead and Load Capacity

Model	Motor Output (W)	Lead (mm)	Max. Load Capacity		Rated Thrust (N)	Stroke (mm)
			Horizontal (kg)	Vertical (kg)		
RCA-RGS4D-①-20-12-②-③-④-⑤	20	12	3.0	0.5	18.9	50~300 (50mm increments)
RCA-RGS4D-①-20-6-②-③-④-⑤		6	6.0	1.5	37.7	
RCA-RGS4D-①-20-3-②-③-④-⑤		3	12.0	3.5	75.4	
RCA-RGS4D-①-30-12-②-③-④-⑤	30	12	4.0	1.0	28.3	
RCA-RGS4D-①-30-6-②-③-④-⑤		6	9.0	2.5	56.6	
RCA-RGS4D-①-30-3-②-③-④-⑤		3	18.0	6.0	113.1	

Legend ① Encoder ② Stroke ③ Compatible controller ④ Control length ⑤ Options

Stroke and Maximum Speed

Stroke	50 ~ 300 (50mm increments)	
	Lead	50 ~ 300 (50mm increments)
12		600
6		300
3		150

(Unit: mm/s)

Encoder & Stroke List

② Stroke (mm)	Standard Price			
	① Encoder			
	Incremental		Absolute	
	Motor Output (W)		Motor Output (W)	
	20W	30W	20W	30W
50	-	-	-	-
100	-	-	-	-
150	-	-	-	-
200	-	-	-	-
250	-	-	-	-
300	-	-	-	-

④ Cable List

Type	Cable Symbol	Standard Price
Standard	P (1m)	-
	S (3m)	-
	M (5m)	-
Special Lengths	X06 (6m) ~ X10 (10m)	-
	X11 (11m) ~ X15 (15m)	-
	X16 (16m) ~ X20 (20m)	-
	R01 (1m) ~ R03 (3m)	-
Robot Cable	R04 (4m) ~ R05 (5m)	-
	R06 (6m) ~ R10 (10m)	-
	R11 (11m) ~ R15 (15m)	-
	R16 (16m) ~ R20 (20m)	-

* See page A-39 for cables for maintenance.

⑤ Option List

Name	Option Code	See Page	Standard Price
Foot bracket	FT	→ A-29	-
Home sensor	HS	→ A-32	-
Power-saving	LA	→ A-32	-
Reversed-home	NM	→ A-33	-
Trunnion bracket (back)	TRR	→ A-38	-

* The home sensor (HS) cannot be used on the reversed-home models.

Actuator Specifications

Item	Description
Drive System	Ball screw ø10mm C10 grade
Positioning Repeatability	±0.02mm
Lost Motion	0.1mm or less
Guide	Single guide (guide rod diameter ø10mm, Ball bush type)
Rod Diameter	ø20mm
Non-rotating accuracy of rod	±0.05 deg
Ambient Operating Temp./Humidity	0 ~ 40°C, 85% RH or less (non-condensing)

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