

DeviceNet and CANopen expansion modules for MAC motors

The modular construction of JVL's MAC50-141 and MAC800 series of integrated MAC motors makes them particularly well suited for a large number of fieldbus applications. The Devicenet module and the CANopen module are described in this product data sheet. The series also includes a Profibus module. New modules are under development, including for example modules for USB, Ethernet, Bluetooth and Zigbee wireless communication.

The AC-servo motor, encoder, amplifier, positional controller and network module are all built into the motor. The only connections required are a supply voltage and the network cables. A double-supply facility is available in order to ensure that position and parameters are maintained intact for example during an emergency stop. Via Devicenet and CANopen it is possible to access all of the MAC motor's registers.

The Devicenet module (MAC00-FD4) and the CANopen module (MAC00-FC4) are supplied with M12 connectors (IP67) with watertight connection for use in harsh industrial environments.

Modules with other types of connector can be developed to suit customer requirements.

Both modules offer the following features:

- Position, torque, and velocity control
- 4 I/O for version with M12 con-

nectors. 6 inputs and 2 outputs for version with cable glands. All 24V PNP and with opto-couplers.

- I/O can be used for end-of-travel limits and high-speed start/stop
- Hardware and software adjustment of baud rate and address
- Galvanically insulated I/O and network connections
- A selection of standard commands are addressable.

Devicenet Module FD4

The MAC00-FD4 module for the integrated servo motors enables the MAC motors to be used on Devicenet. The device hhhh standard method for controlling position when motion control is used on Devicenet.



At no additional cost, the EDS files, function blocks and program examples for the most commonly used Devicenet PLC's from Omron and Allen Bradley/Rockwell can be downloaded from www.jvl.dk. The function blocks are fully documented so they can be readily adapted for use with other PLC types.

CANopen Module MAC00-FC4

The MAC00-FC4 module for the integrated servo motors enables the MAC motors to be used on a CANopen or CANbus network. See more on www.can-cia.org.

The CAN module features:

- CANbus/CANopen DS 301 V3.0
- CANopen DSP 402 V2.0
- Baud rates from 10 to 1000kbit



Devicenet

DeviceNet is a proven, stable network technology designed to meet the performance and reliability requirements of the industrial environment. DeviceNet uses CAN (Controller Area Network) for its data link layer, and CIP™ (Common Industrial Protocol) for the upper-layers of the network. DeviceNet is an open standard managed by ODVA (see www.odva.org) and accepted by international standards bodies around the world. DeviceNet is supported by vendors around the world





and is the most used network for Allen Bradley/Rockwell and Omron PLC. DeviceNet is a digital, multi-drop network that connects and serves as a communication network between industrial controllers and I/O devices. Each device and/or controller is a node on the network. DeviceNet is a producer-consumer network that supports multiple communication hierarchies and message prioritization. DeviceNet systems can be configured to operate in a master-slave or a distributed con-

trol architecture using peer-to-peer communication. DeviceNet systems offer a single point of connection for configuration and control by supporting both I/O and explicit messaging. DeviceNet also has the unique feature of having power on the network. This allows devices with limited power requirements to be powered directly from the network, reducing connection points and physical size.

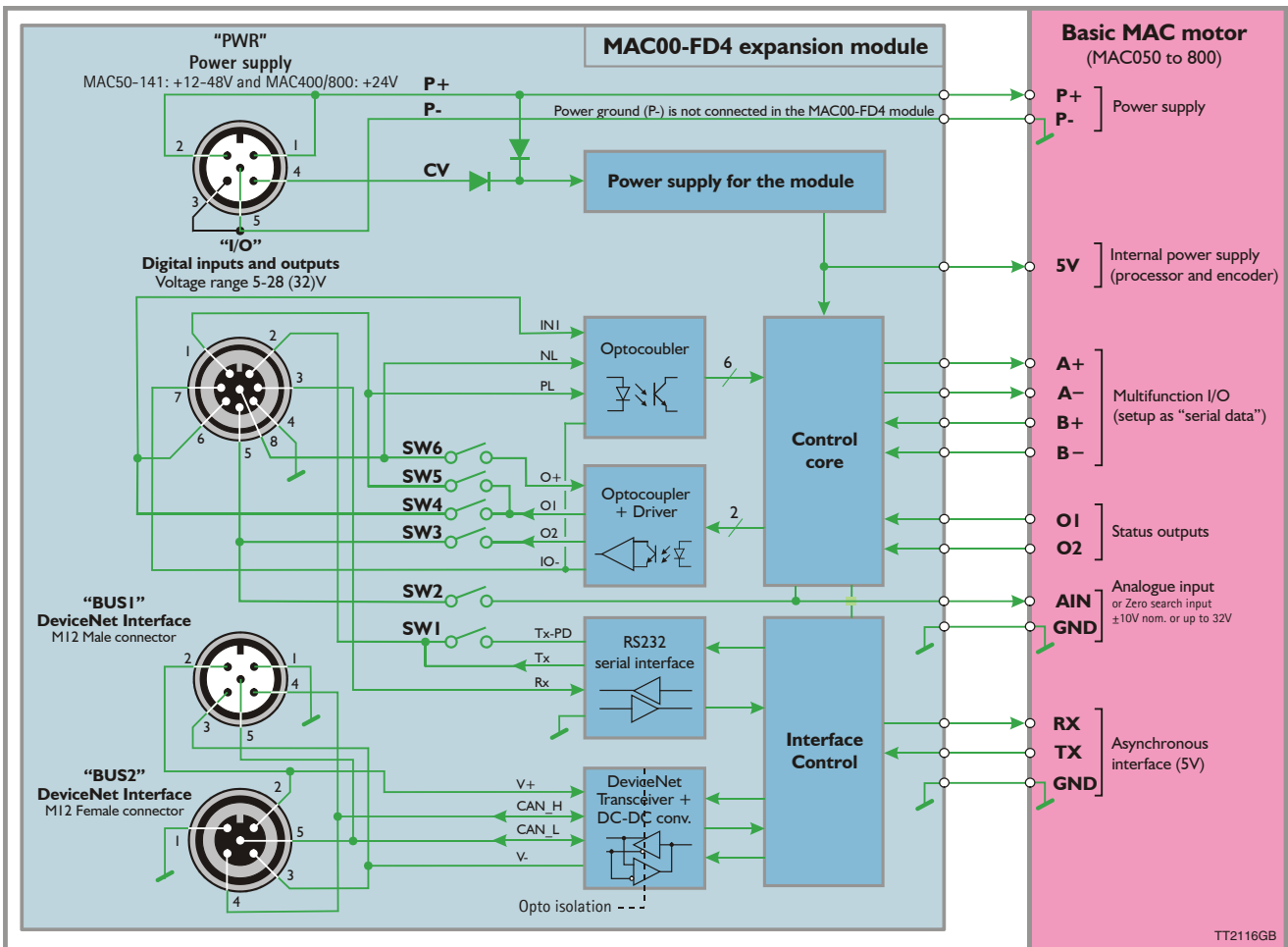
Comparison Chart

| | DEVICENET | CANOPEN | CANBUS | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|-----------------------|---|---|---|---------|----------------|---------|----------------|---|-------|-----------------|--------|---------------|-------|----------------|--------|--------------|-------|----------------|--------|-------------|--------|--------------|---------|--------------|---|-------|-----------------|--------|---------------|-------|----------------|--------|--------------|-------|----------------|--------|-------------|--------|--------------|---------|--------------|
| Nodes | Up to 64 Nodes | Up to 128 | Extended frame up to 2 ²⁹ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Network Length | Selectable end-to-end network distance varies with speed <table border="1"> <tr> <td>125 Kbs</td> <td>500 m (1,640 ft)</td> </tr> <tr> <td>250 Kbs</td> <td>250 m (820 ft)</td> </tr> <tr> <td>500 Kbs</td> <td>100 m (328 ft)</td> </tr> </table> | 125 Kbs | 500 m (1,640 ft) | 250 Kbs | 250 m (820 ft) | 500 Kbs | 100 m (328 ft) | Selectable end-to-end network distance varies with speed: <table border="1"> <tr> <td>10Kbs</td> <td>5000m(16404ft.)</td> <td>125Kbs</td> <td>500m(1640ft.)</td> </tr> <tr> <td>20Kbs</td> <td>2500m(8202ft.)</td> <td>250Kbs</td> <td>250m(820ft.)</td> </tr> <tr> <td>50Kbs</td> <td>1000m(3280ft.)</td> <td>500Kbs</td> <td>100m(328ft)</td> </tr> <tr> <td>100Kbs</td> <td>700m(2996ft)</td> <td>1000Kbs</td> <td>30m(98.4ft.)</td> </tr> </table> | 10Kbs | 5000m(16404ft.) | 125Kbs | 500m(1640ft.) | 20Kbs | 2500m(8202ft.) | 250Kbs | 250m(820ft.) | 50Kbs | 1000m(3280ft.) | 500Kbs | 100m(328ft) | 100Kbs | 700m(2996ft) | 1000Kbs | 30m(98.4ft.) | Selectable end-to-end network distance varies with speed: <table border="1"> <tr> <td>10Kbs</td> <td>5000m(16404ft.)</td> <td>125Kbs</td> <td>500m(1640ft.)</td> </tr> <tr> <td>20Kbs</td> <td>2500m(8202ft.)</td> <td>250Kbs</td> <td>250m(820ft.)</td> </tr> <tr> <td>50Kbs</td> <td>1000m(3280ft.)</td> <td>500Kbs</td> <td>100m(328ft)</td> </tr> <tr> <td>100Kbs</td> <td>700m(2996ft)</td> <td>1000Kbs</td> <td>30m(98.4ft.)</td> </tr> </table> | 10Kbs | 5000m(16404ft.) | 125Kbs | 500m(1640ft.) | 20Kbs | 2500m(8202ft.) | 250Kbs | 250m(820ft.) | 50Kbs | 1000m(3280ft.) | 500Kbs | 100m(328ft) | 100Kbs | 700m(2996ft) | 1000Kbs | 30m(98.4ft.) |
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| Data Packets | 0-8 bytes | 0-8 bytes | 0-8 bytes | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Bus Topology | Linear (trunkline/dropline); power and signal on the same network cable | Linear (trunkline/dropline); power and signal on the same network cable | Linear (trunkline/dropline); power and signal on the same network cable | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Bus Addressing | Peer-to-Peer with Multi-Cast (one-to-many); Multi-Master and Master/Slave special case; polled or change-of-state (exception-based) | Master/Slave Producer/Consumer | None | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Motor Connector Description

| | | Connector | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|-----------------------|----------------------|---|---------------|---------------|------------|--------------------|----------------|----------------|-----|---------------|
| BUS1 (Bus in) | CANopen | M12 Male 5pin | CAN_SHLD | CAN_V+ | CAN_GND | CAN_H | CAN_L | | | |
| | DeviceNet |  | Drain | V+ | V- | CAN_H | CAN_L | | | |
| | Cable Color code | | bare | red | black | white | blue | | | |
| BUS2 (Bus out) | CANopen | M12 Female 5pin | CAN_SHLD | CAN_V+ | CAN_GND | CAN_H | CAN_L | | | |
| | DeviceNet |  | Drain | V+ | V- | CAN_H | CANL | | | |
| | Cable Color code | | bare | red | black | white | blue | | | |
| PWR (Power supply) | CANopen DeviceNet | M12 Male 5 pin | P+ (12-48VDC) | P+ (12-48VDC) | P- (GND) | CV Control voltage | P- (GND) | | | |
| | Cable Color code |  | Brown | White | Blue | Black | Grey | | | |
| I/O | CANopen DeviceNet | M12 Female 8 pin | IOC. PL or O1 | Tx (RS232) | Rx (RS232) | GND (RS232) | IOA. AIN or O2 | IOB. IN1 or O1 | IO- | IOD. NL or O+ |
| | Cable Color code |  | White | Brown | Green | Yellow | Grey | Pink | | Red |

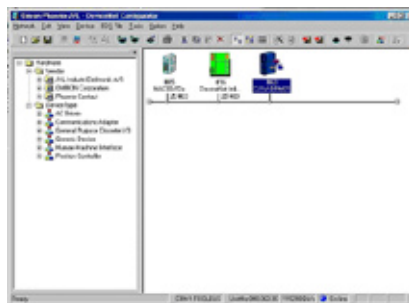




Block diagram of MAC00-FD4 with MAC motor

Easy start with sample code for Omron and Allen Bradley PLC

At no additional cost, the Expansion Module is supplied with EDS files, function blocks and program examples for the most commonly used DeviceNet PLC's from Omron (CJ1) and Allen Bradley platform (SLC500 and Logix). The function blocks are fully documented so they can be readily adapted for use with other PLC types.

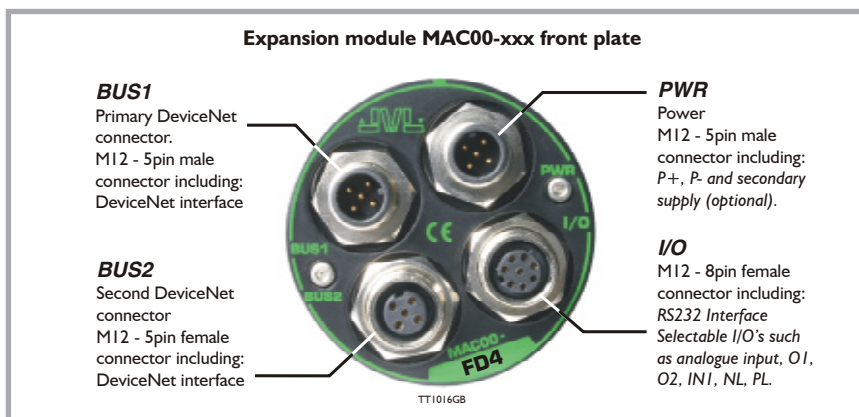


Easy installation with M12 connector

JVL MACmotor expansion board MAC00-FD4 and FC4 use a standard M12 connector with 5 and 8 pin. To ease installation there is one connector for BUS In and one for BUS Out.

I/O possibilities

The expansion boards are equipped with 6 inputs and 2 outputs, all galvanically isolated. Because of the limited number of pins in the M12 connector only some of the I/O's are available in the connector. With an internal dipswitch it is possible to select between O1, O2, AIN, INI, NL, PL, IO- and IO+ on 4 of the pins. Contact JVL if other configurations are required. For OEM use, a solution with cable glands or customer specified connector with all I/O's supported can be delivered.

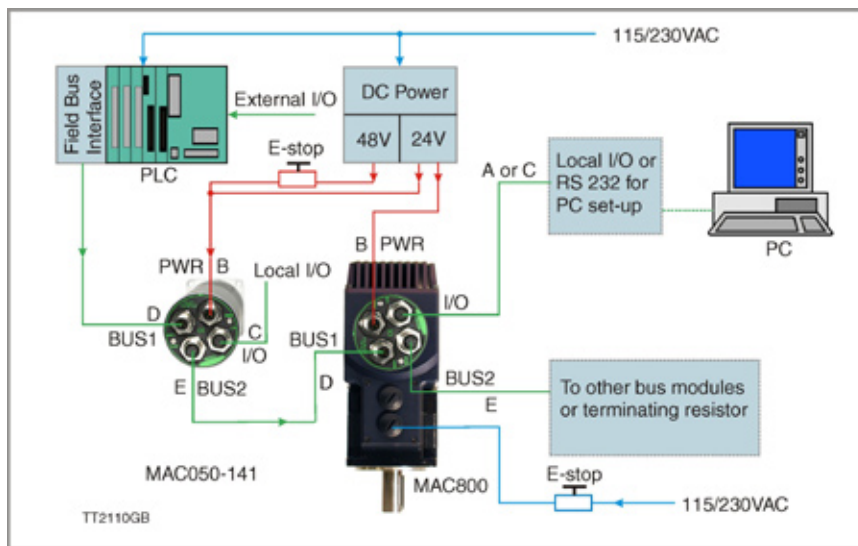




Cables and accessories

| Cable and accessory | Description M12 IP67 (Standard cable with shield) | Connector | Type code | Picture |
|---------------------|---|-------------|------------------|---------|
| A | RS232 programming cable | I/O | RS232-M12-1-5-8 | |
| B | Power cable | PWR | WI1000-M12F5VxxN | |
| C | IO cable | I/O | WI1000-M12M8VxxN | |
| D | BUS1 cable. | BUS1 | WI1006-M12F5SxxR | |
| E | BUS2 cable. | BUS2 | WI1006-M12M5SxxR | |
| F | Protection cap for M12 male | BUS1 or PWR | WI1000-M12MCAP1 | |
| G | Protection cap for M12 female | BUS2 or I/O | WI1000-M12FCAP1 | |
| H | Connector 5 pin female straight solder terminals | BUS1 or PWR | WI1008-M12F5SS1 | |
| I | Connector 5 pin male straight solder terminals | BUS2 | WI1008-M12M5SS1 | |

xx indicates cable length 05 or 20 meters (flying leads)



Two MAC motors in a network

Technical specifications

Absolute maximum rating

| Description | Min | Typ | Max | Absolute Max | Unit |
|----------------------|-----|-----|-----|--------------|-------|
| CV Current@ 24VDC* | | 250 | 400 | | mA |
| Voltage O+ | 10 | | 30 | 32 | VDC |
| Voltage P+ | 12 | | 48 | 50 | VDC |
| Control Voltage CV | 12 | | 48 | 50 | VDC |
| Input IN1-4, NL,PL | 4,5 | | 28 | 32 | VDC |
| Input Impedance | | 5,6 | | | kOhms |
| Input current @24V | | 4,3 | | | mA |
| Analoque input ** | -10 | | 10 | 32 | VDC |
| Output O1, O2 | 0 | | 30 | 32 | VDC |
| Output current O1,O2 | | | 25 | | mA |

* Only expansion module. Remember to add the current for the basic motor

** Resolution 11bit+sign for MAC800 and 9bit+sign for MAC050-MAC141

CANopen Features

| Features | Contacts |
|-----------------------------|--|
| NMT | Slave |
| Error control | Node guarding, Heartbeat |
| Node ID | Hardware switch, Software switch |
| No. of PDO | 10 Rx, 11Tx |
| PDO modes | Event-triggered, Time-triggered, Remotely-requested, Sync (cyclic), Sync (acyclic) |
| PDO linking | Yes |
| PDO mapping | Static |
| No. of SDO | 1 Server, 1 Client |
| Emergency message | Yes |
| Supported application layer | CiA DS 301 V 3.0 CiA DS 301 V 4.02 |
| Supported frameworks | None |
| Supported profiles | CiA DSP 402 V 2.0 |

Protection

The Modules are supplied with M12 connectors (IP67) with watertight connection for use in industrial environments. Modules with other types of connector can be developed to suit customer requirements.



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