

RCP3-TA5C

ROBO Cylinder Table Type Motor Unit Coupled 55mm Width Pulse Motor Ball Screw

■ Configuration: **RCP3** — **TA5C** — **I** — **35P** — — — — —

Series — Type — Encoder — Motor — Lead — Stroke — Compatible Controllers — Cable Length — Option

I: Incremental
 * The simple absolute encoder is also considered type "I".

35P: Pulse motor 10: 10mm
 35 □ size 5: 5mm
 2.5: 2.5mm

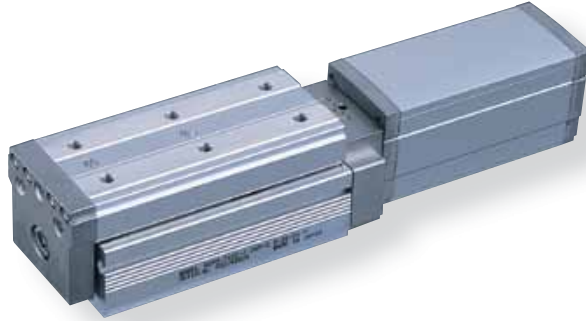
25: 25mm
 100: 100mm (25mm pitch increments)

P1: PCON
 RPCON
 PSEL
 P3: PMEC
 PSEP

N: None
 P: 1m
 S: 3m
 M: 5m
 X □ □: Custom

See Options below

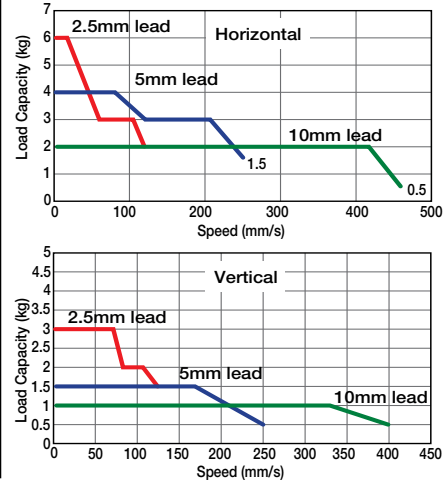
* See page Pre-35 for an explanation of the naming convention.



Technical References P. A-5

- POINT** Notes on Selection
- (1) Since the RCP3 series use a pulse motor, the load capacity decreases at high speeds. Check in the Speed vs. Load Capacity graph to see if your desired speed and load capacity are supported.
 - (2) Please note that the maximum speed is different when used horizontally versus vertically.
 - (3) The load capacity is based on operation at an acceleration of 0.3G (0.2G for the 2.5mm-lead model, or when used vertically). This is the upper limit of the acceleration.

■ Speed vs. Load Capacity
 Due to the characteristics of the Pulse motor, the RCP3 series' load capacity decreases at high speeds. In the table below, check if your desired speed and load capacity are supported.



Actuator Specifications

Lead and Load Capacity

(Note 1) Please note that the maximum load capacity decreases as the speed increases.

Model	Lead (mm)	Max. Load Capacity (Note 1)		Maximum Push Force (N) (Note 2)	Stroke (mm)
		Horizontal (kg)	Vertical (kg)		
RCP3-TA5C-I-35P-10-①-②-③-④	10	~ 2	~ 1	34	25~100 (25mm increments)
RCP3-TA5C-I-35P-5-①-②-③-④	5	~ 4	~ 1.5	68	
RCP3-TA5C-I-35P-2.5-①-②-③-④	2.5	~ 6	~ 3	136	

Legend ① Stroke ② Compatible controller ③ Cable length ④ Options

(Note 2) See page A-66 for pushing force graphs.

Stroke and Maximum Speed

Lead	Stroke	25 ~ 100 (25mm increments)
		10
5		250
2.5		125

(Unit: mm/s)

① Stroke List

Stroke (mm)	Standard Price
25	-
50	-
75	-
100	-

③ Cable List

Type	Cable Symbol	Standard Price
Standard (Robot Cables)	P (1m)	-
	S (3m)	-
	M (5m)	-
Special Lengths	X06 (6m) ~ X10 (10m)	-
	X11 (11m) ~ X15 (15m)	-
	X16 (16m) ~ X20 (20m)	-
		-

* The standard cable is the motor-encoder integrated robot cable.
 * See page A-39 for cables for maintenance.

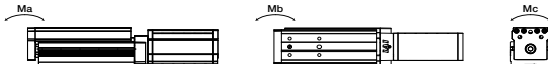
④ Option List

Name	Option Code	Standard Price	Standard Price
Brake	B	→ A-25	-
Cable exit direction (Top)	CJT	→ A-25	-
Cable exit direction (Right)	CJR	→ A-25	-
Cable exit direction (Left)	CJL	→ A-25	-
Cable exit direction (Bottom)	CJB	→ A-25	-
Reversed-home	NM	→ A-33	-

Actuator Specifications

Item	Description
Drive System	Ball screw ø8mm C10 grade
Positioning Repeatability	±0.02mm
Lost Motion	0.1mm or less
Base	Material: Material: Aluminum (special alumite treated)
Allowable Static Moment	Ma: 25.5 N·m Mb: 36.5 N·m Mc: 56.1 N·m
Allowable Dynamic Moment (*)	Ma: 6.57 N·m Mb: 9.32 N·m Mc: 14.32 N·m
Overhang Load Length	Within the load moment range
Ambient Operating Temp./Humidity	0~40°C, 85% RH or less (non-condensing)

(*) Based on a 5,000km service life.
 Directions of Allowable Load Moments

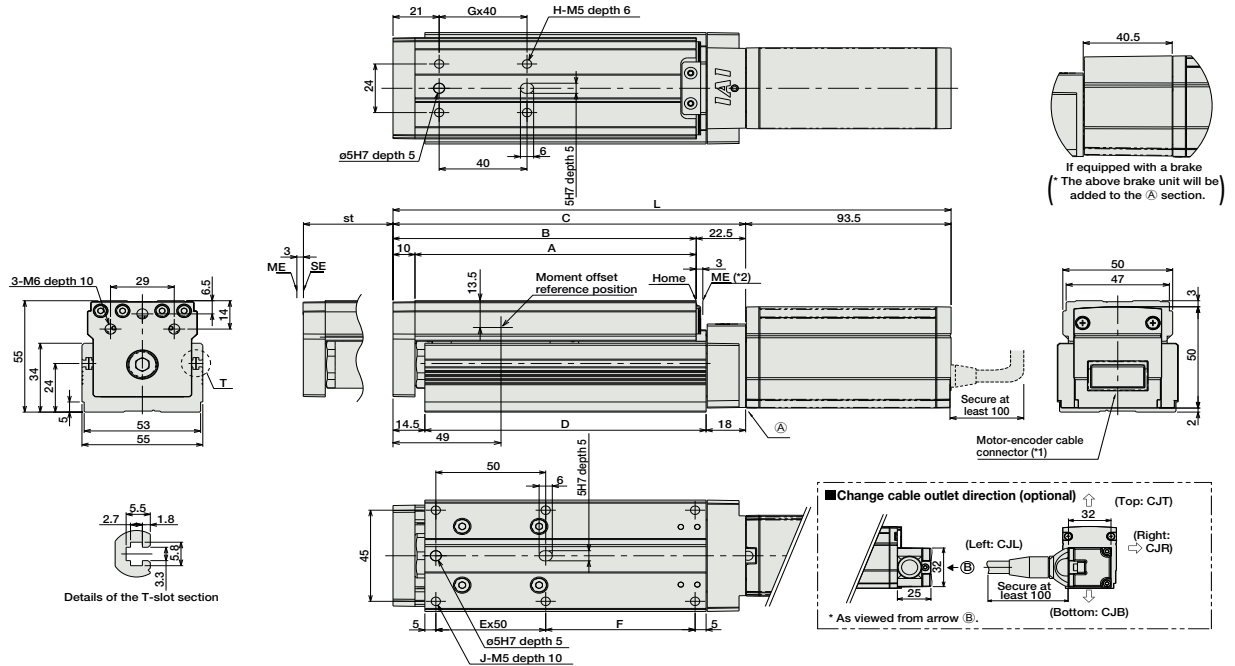


273 RCP3-TA5C

- Slider Type
- Mini
- Standard
- Controllers Integrated
- Rod Type
- Mini
- Standard
- Controllers Integrated
- Table/Arm/Flat Type
- Mini
- Standard
- Gripper/Rotary Type
- Linear Servo Type
- Cleanroom Type
- Splash Proof
- Controllers
- PMEC/AMEC
- PSEP/ASEP
- ROBO NET
- ERC2
- PCON
- ACON
- SCON
- PSEL
- ASEL
- SSEL
- XSEL
- Pulse Motor
- Servo Motor (24V)
- Servo Motor (200V)
- Linear Servo Motor

Dimensions

For Special Orders P. A-9



(*1) The motor-encoder cable (integrated) is connected. (See page A-39 for details on cables.)
 (*2) After homing, the slider moves to the ME; therefore, please watch for any interference with the surrounding objects.
 ME: Mechanical end
 SE: Stroke end

■ Dimensions/Weight by Stroke * Adding a brake will increase the actuator's weight by 0.3kg.

Stroke	No Brake	25	50	75	100
		Brake-Equipped	269.5	294.5	319.5
L					
A		103	128	153	178
B		113	138	163	188
C		135.5	160.5	185.5	210.5
D		103	128	153	178
E		1	1	2	2
F		43	68	43	68
G		1	1	2	2
H		4	4	6	6
J		6	6	8	8
Weight (kg)		1.2	1.4	1.5	1.7

② Compatible Controllers

The RCP3 series actuators can operate with the controllers below. Select the controller according to your usage.

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Page
Solenoid Valve Type		PMEC-C-3SPI-NP-2-①	Easy-to-use controller, even for beginners	3 points	AC100V AC200V	See P481	-	→ P477
		PSEP-C-3SPI-NP-2-0	Operable with same signal as solenoid valve. Supports both single and double solenoid types. No homing necessary with simple absolute type.					→ P487
Splash-Proof Solenoid Valve Type		PSEP-CW-3SPI-NP-2-0						
Positioner Type		PCON-C-3SPI-NP-2-0	Positioning is possible for up to 512 points	512 points	DC24V	2A max.	-	→ P525
Safety-Compliant Positioner Type		PCON-CG-3SPI-NP-2-0						
Pulse Train Input Type (Differential Line Driver)		PCON-PL-3SPI-NP-2-0	Pulse train input type with differential line driver support	(-)	DC24V	2A max.	-	→ P525
Pulse Train Input Type (Open Collector)		PCON-PO-3SPI-NP-2-0	Pulse train input type with open collector support					
Serial Communication Type		PCON-SE-3SPI-N-0-0	Dedicated to serial communication	64 points				
Field Network Type		RPCON-3SP	Dedicated to field network	768 points				→ P503
Program Control Type		PSEL-C-1-3SPI-NP-2-0	Programmed operation is possible. Operation is possible on up to 2 axes	1500 points				→ P557

* This is for the single-axis PSEL.
 * ① is a placeholder for the power supply voltage (1: 100V, 2: 100~240V).

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