

Power-saving Technical References

P. A-**5**

- (1) The horizontal load capacity is based on the use of a guide to prevent any radial and/or moment load on the rod.
 - If no guide will be installed, see the Tip Load vs. Service Life graph (ightarrow page A-82).
- (2) The load capacity is based on operation at an acceleration of 0.2G. This is the upper limit of the acceleration.
- (3) This model uses a lead screw. Please ensure that your usage is appropriate for its characteristics. (See page Pre-42 for more information.)

Actuator Specifications ■ Lead and Load Capacity Stroke and Maximum Speed Max. Load Capacity 30 (mm) Feed Screw Lead (mm) hing bility Stroke Model Output (v Thrust (N RCA2-GD3N-I-10-4S-30-1-2-3 0.25 0.125 25.1 4 200 Screw RCA2-GD3N-I-10-2S-30-1 - 2 - 3 10 2 0.5 0.25 2 100 50.3 ±0.05 30 Lead RCA2-GD3N-I-10-1S-30-1 - 2 - 3 1 1 0.5 100.5 50 (Unit: mm/s) Legend ① Compatible controller ② Cable length ③ Options

Stroke List	
	Standard Price
Ot ()	
Stroke (mm)	Feed Screw
	Lead Screw
30	<u>-</u>

Cable Symbol	Standard Price
P (1m)	-
S (3m)	-
M (5m)	-
X06 (6m) ~ X10 (10m)	-
X11 (11m) ~ X15 (15m)	-
X16 (16m) ~ X20 (20m)	-
	Cable Symbol P (1m) S (3m) M (5m) X06 (6m) ~ X10 (10m) X11 (11m) ~ X15 (15m)

* The RCA2 comes standard with a robot cable.

② Coble List

* See page A-39 for cables for maintenance.

③ Option List			
Name	Option Code	See Page	Standard Price
Connector cable exit direction	K2	→ A-32	-
Power-saving	LA	→ A-32	-

Actuator Specification	ons		
Item	Description		
Drive System	Lead screw ø4mm C10 grade		
Lost Motion	0.3mm or less (initial value)		
Frame	Material: Aluminum (white alumite treated)		
Ambient Operating Temp./Humidity	0~40°C, 85% RH or less (non-condensing)		
Service Life	Horizontal: 10 million cycles Vertical: 5 million cycles		

 $189_{\scriptscriptstyle \sf RCA2\text{-}GD3N}$

PMEC /AMEC PSEP /ASEP ROBO NET PCON ACON PSEL ASEL SSEL

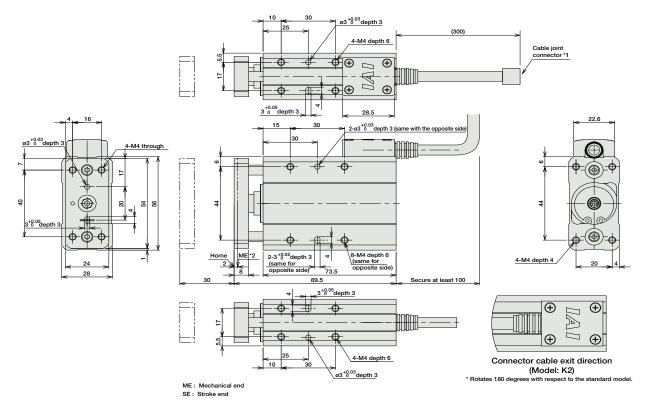
Rod Type

Mini

Standard

Controllers
Integrated





*1 A motor-encoder cable is connected here. See page A-39 for details on cables.

*2 When homing, the rod moves to the mechanical end; therefore, please watch for any interference with the surrounding objects.

■ Dimensions/W	Veight by Stroke
Stroke	30
Weight (kg)	0.41

Name	External View	Model	Description	Max. Positioning Points	Input Voltage	Power Supply Capacity	Standard Price	See Pag
0.1		AMEC-C-10I①-NP-2-1	Easy-to-use controller, even for beginners		AC100V	2.4A rated	-	→ P47
Solenoid Valve Type	1	ASEP-C-10I①-NP-2-0	Operable with same signal as solenoid valve. Supports both single and double solenoid types.	3 points			-	, P40
Splash-Proof Solenoid Valve Type	1	ASEP-CW-10I①-NP-2-0	No homing necessary with simple absolute type.			(Standard) 1.3A rated 4.4A max. (Power-saving) 1.3A rated 2.5A max.	-	→ P487
Positioner Type		ACON-C-10I①-NP-2-0	Positioning is possible for up to 512 points	512 points			-	→ P535
Safety-Compliant Positioner Type		ACON-CG-10I①-NP-2-0	r contouring to processor for up to 012 points	0.2 points			-	
Pulse Train Input Type (Differential Line Driver)	Q.	ACON-PL-10I①-NP-2-0	Pulse train input type with differential line driver support	(-)	DC24V		-	
Pulse Train Input Type (Open Collector)	ē.	ACON-PO-10I①-NP-2-0	Pulse train input type with open collector support	()			-	
Serial Communication Type		ACON-SE-10I①-N-0-0	Dedicated to serial communication	64 points			-	
Field Network Type		RACON-10①	Dedicated to field network	768 points			-	→ P50
Program Control Type		ASEL-C-1-10I①-NP-2-0	Programmed operation is possible Operation is possible on up to 2 axes	1500 points			-	→ P56

IAI

190 RCA2-GD3N



Mini
Standard
Controllers integrated
Rod
Type
Mini
Standard
Controllers integrated
Table/Arm
Flat Type

PMEC /AMEC PSEP /ASEP /ASEP ROBO NET ERC2 PCON ACON SCON PSEL ASEL SSEL